



# POSIDONIA

ULTRA-DEEP, LONG-RANGE USBL

POSIDONIA USBL, acoustic positioning system for high-accuracy/ultra long-range positioning of subsea vehicles. It is unique to the market with its combination of CHIRP multi-frequency coded signals and digital processing techniques.

## FEATURES

- Extremely long-range up to 8,000 m and accurate up to 0.3% of slant range\*
- Low frequency band, CHIRP modulation, robust to noise and multipath
- Compatible with OCEANO Transponders range
- Compatible with IXSEA's inertial sensors (PHINS OCTANS, HYDRINS...)

\*Performance depends on environment/noise conditions

## BENEFITS

- Deep tow operations with no need for second tracking vessel
- High-performance even in extremely adverse conditions
- A wide range of transponders available for all applications
- Added flexibility and improved performance



**APPLICATIONS**

- Deep towfish tracking
- AUV, ROV and any deep sea vehicle tracking
- Pipe/cable laying operations

# POSIDONIA

## TECHNICAL SPECIFICATIONS

### PERFORMANCE <sup>(1)</sup>

<b>Accuracy</b>	0.3% of slant range
<b>Depth</b>	6,000 m
<b>Range</b>	8,000 m

Optimum performance of POSIDONIA<sup>(1)</sup> can be achieved when used in conjunction with other IXSEA Navigation equipment (OCTANS gyrocompass or PHINS inertial navigation system as a single high-accuracy source of heading and attitude data).

### PHYSICAL CHARACTERISTICS

	<b>Deployable</b>	<b>Flush</b>
<b>Acoustic antenna</b>		
Height	420 mm	320 mm
Width Ø	580 mm	800 mm
Weight in air	34 kg	150 kg

### PHYSICAL CHARACTERISTICS

	<b>Deployable</b>	<b>Flush</b>
<b>Transmitter</b>		
Source level	190 ± 3 dB ref 1µPa	192 ± 3 dB ref 1µPa
Bandwidth	8 - 14 kHz	8 - 14 kHz
<b>Receiver</b>		
Bandwidth	14 - 18 kHz	14 - 18 kHz
Signal	M-FSK	M-FSK
<b>Processing</b>		
Processing Gain	19 dB	19 dB
Navigation / Control	Windows™ compatible	Windows™ compatible

### INTERFACES

<b>Protocols</b>	Industry standard (NMEA0183, binary)
<b>GPS</b>	Any external GPS, DGPS, and RTK receiver
<b>Pitch, Roll, Heading</b>	input IXSEA's inertial sensors and standard sensors
<b>Sound velocity</b>	Sound velocity correction (ray bending, velocity error)
<b>Pressure sensor</b>	External pressure sensor, optional OCEANO transponder sensor
<b>External synchronisation</b>	Input / Output

(1) Performance depends on environment / noise conditions